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Hamiltonian Formulation of 2 Bounded Immiscible Media with Constant Non-Zero Vorticities and a Common Interface

Alan Compelli

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Abstract

We examine a 2-dimensional water-wave system, with gravitationally induced waves, consisting of a lower medium bound underneath by an impermeable flat bed and an upper medium bound above by an impermeable lid such that the 2 media have a free common interface. Both media have constant density and constant (non-zero) vorticity. By examining the governing equations of the system we calculate the Hamiltonian of the system in terms of its conjugate variables and perform a variable transformation to show that it has canonical Hamiltonian structure.

1 Introduction

In 1968 Zakharov published a paper [1] showing the canonical Hamiltonian structure of an infinitely deep irrotational fluid system, i.e. with zero vorticity, with a free surface with gravitationally induced waves. Further relevant studies of the irrotational case were carried out in [2], [3], [4], [5], [6]. At the beginning of the 19th century Gernstner [7] had studied vorticity and more recently there have been several papers of interest which consider the rotational case, i.e. with non-zero constant vorticity, e.g. [8], [9], [10], [11], [12], [13], [14], [15], [16], [17]. In particular Constantin et al. [18] showed that a consideration of non-zero vorticity gives a *nearly* Hamiltonian structure

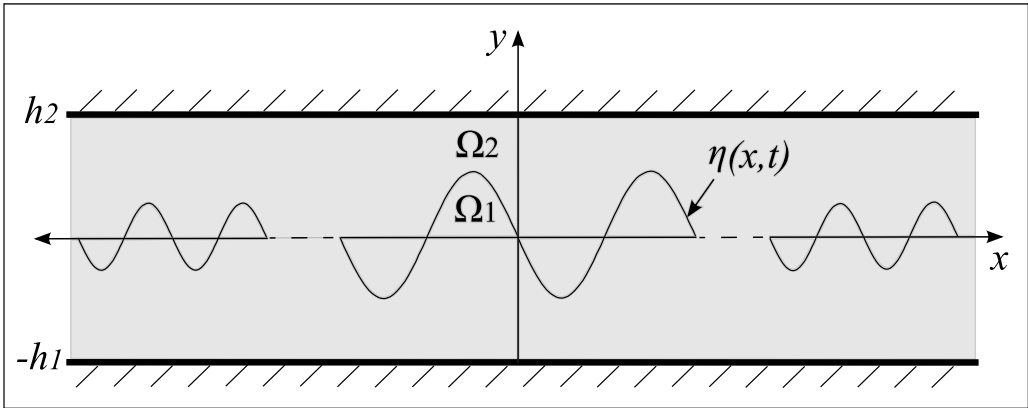


Figure 1: The system under study

(with a linear dependency on a vorticity term). Wahlén [19] then showed that, in fact, the system does indeed have *fully* Hamiltonian structure, which can be transformed into canonical form.

A consideration of a system consisting of 2 unbounded media with a free common interface was given by Benjamin and Bridges [20], [21]. Craig et al. [22], [23] considered an irrotational system consisting of a lower medium bound underneath by a flat bed and an upper medium bound above by an impermeable lid such that the 2 media have a free common interface and also the case in which the upper media itself has a free surface. The aim of this paper is to show that, in the rotational case, the 2 media bounded system has canonical Hamiltonian structure.

2 Preliminaries

As per Figure 1 we define the lower medium Ω_1 as the domain $\{(x, y) \in \mathbb{R}^2 : -h_1 < y < \eta(x, t)\}$, the upper medium Ω_2 as the domain $\{(x, y) \in \mathbb{R}^2 : \eta(x, t) < y < h_2\}$ and the entire system Ω as the domain $\{(x, y) \in \mathbb{R}^2 : -h_1 < y < h_2\}$ where $\{y = \eta(x, t)\}$ describes the elevation of the common interface. The subscript c will be used to denote evaluation at the common interface.

We use the subscript notation $i = \{1, 2\}$ to represent the lower and upper media respectively and thus can consider a velocity potential φ_i which is

defined by:

$$\begin{cases} u_i = \partial_x \varphi_i - \omega_i y \\ v_i = \partial_y \varphi_i \end{cases} \quad (1)$$

where non-lateral velocity flow, with propagation in the positive x -direction, is given by $\mathbf{V}_i(x, y, z) = (u_i, v_i, 0)$ and ω_1 and ω_2 are the respective non-zero constant vorticities.

Additionally, the stream function ψ_i is introduced, defined by:

$$\begin{cases} u_i = -\partial_y \psi_i \\ v_i = \partial_x \psi_i. \end{cases} \quad (2)$$

ρ_1 and ρ_2 are the respective constant densities of the lower and upper media and stability is given by the condition that $\rho_1 > \rho_2$.

We assume that for large $|x|$ the amplitude of η attenuates and hence make the following assumptions

$$\lim_{|x| \rightarrow \infty} \eta(x, t) = 0, \quad (3)$$

$$\lim_{|x| \rightarrow \infty} \varphi_i(x, y, t) = 0, \quad (4)$$

and

$$-h_1 < \eta(x, t) < h_2 \text{ for all } x \text{ and } t. \quad (5)$$

3 Governing Equations

We write Euler's momentum-conserving equation as:

$$\partial_t \mathbf{V}_i + (\mathbf{V}_i \cdot \nabla) \mathbf{V}_i = -\frac{1}{\rho_i} \nabla P_i + \mathbf{g} \quad (6)$$

where $P_i = \rho_i g y + p_{\text{atm}} + p_i$ is the pressure at a depth y , p_{atm} is (constant) atmospheric pressure, p_i is the dynamic pressure due to the wave motion, g is the acceleration due to gravity (where y points in the opposite direction to the center of gravity) and \mathbf{g} is the force due to gravity per unit mass.

Applying Equations (1) and (2) this can be written as

$$\nabla \left(\partial_t \varphi_i + \frac{1}{2} (\nabla \psi_i)^2 - \omega_i \psi_i \right) = \nabla \left(-gy - \frac{p_i}{\rho_i} \right) \quad (7)$$

where $\nabla = (\partial_x, \partial_y)$.

At the interface $p_1 = p_2 = p_c$ therefore we write Euler's equation in terms of the velocity potentials, stream functions, densities and vorticities as the energy conserving equality

$$\begin{aligned} \rho_1 \nabla \left((\partial_t \varphi_1)_c + \frac{1}{2} (\nabla \psi_1)_c^2 - \omega_1 \chi_1 + g\eta \right) \\ - \rho_2 \nabla \left((\partial_t \varphi_2)_c + \frac{1}{2} (\nabla \psi_2)_c^2 - \omega_2 \chi_2 + g\eta \right) = 0, \end{aligned} \quad (8)$$

where χ_i is the stream function evaluated at the interface.

The following Bernoulli condition at the interface follows from assumptions (3) and (4):

$$\rho_1 \left((\partial_t \varphi_1)_c + \frac{1}{2} (\nabla \psi_1)_c^2 - \omega_1 \chi_1 + g\eta \right) = \rho_2 \left((\partial_t \varphi_2)_c + \frac{1}{2} (\nabla \psi_2)_c^2 - \omega_2 \chi_2 + g\eta \right). \quad (9)$$

We will also use the following kinematic boundary conditions

$$\begin{cases} \partial_t \eta - \partial_x \eta (\omega_i \eta - (\partial_x \varphi_i)_c) - (\partial_y \varphi_i)_c = 0 \\ \partial_y (\varphi_1)_b = \partial_y (\varphi_2)_l = 0 \end{cases} \quad (10)$$

noting that $\mathbf{V}_1(x, -h_1, 0) = (u_1, 0, 0)$ and $\mathbf{V}_2(x, h_2, 0) = (u_2, 0, 0)$, where the subscripts b and l denote evaluation at the bottom (lower boundary) and lid (upper boundary) respectively.

4 Hamiltonian of the System

If we consider the system under study as an irrotational system the Hamiltonian, H , is given by the sum of the kinetic and potential energies as:

$$H = \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta^2 dx. \quad (11)$$

However, as we are concerned with the rotational case the Hamiltonian (noting the additional vorticity related terms) is given by:

$$\begin{aligned}
H = & \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta^2 dx \\
& - \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1 y \partial_x \varphi_1 dy dx - \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2 y \partial_x \varphi_2 dy dx \\
& + \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1^2 y^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2^2 y^2 dy dx. \quad (12)
\end{aligned}$$

Using the Gauss-Green theorem, and introducing $\xi_i := (\varphi_i)_c = \varphi_i(x, \eta(x, t), t)$ as the interface velocity potential, we can write the first 2 terms of (12) as

$$\begin{aligned}
& \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2)^2 dy dx \\
& = \frac{1}{2} \int_{\mathbb{R}} \rho_1 \xi_1 \partial_{\mathbf{n}_1} \varphi_1 \sqrt{1 + (\partial_x \eta)^2} dx - \frac{1}{2} \int_{\mathbb{R}} \rho_2 \xi_2 \partial_{\mathbf{n}_2} \varphi_2 \sqrt{1 + (\partial_x \eta)^2} dx \quad (13)
\end{aligned}$$

where $\partial_{\mathbf{n}_i} \varphi_i$ is the normal derivative of the velocity potential φ_i , at the surface, for an outward normal \mathbf{n}_i .

Next, we introduce the Dirichlet-Neumann operator $G_i(\eta)$ given by (see [3], [23])

$$G_i(\eta) \xi_i = \partial_{\mathbf{n}_i} \varphi_i \sqrt{1 + (\partial_x \eta)^2}, \quad (14)$$

and hence we can write the first 2 (kinetic energy) terms of (12) as

$$\begin{aligned}
& \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2)^2 dy dx \\
& = \frac{1}{2} \int_{\mathbb{R}} \rho_1 \xi_1 G_1(\eta) \xi_1 dx + \frac{1}{2} \int_{\mathbb{R}} \rho_2 \xi_2 G_2(\eta) \xi_2 dx. \quad (15)
\end{aligned}$$

Using the kinematic boundary conditions from (10)

$$\begin{cases} G_1(\eta)\xi_1 = -\partial_x\eta(\partial_x\varphi_1)_c + (\partial_y\varphi_1)_c = \partial_t\eta - \omega_1\eta\partial_x\eta, \\ G_2(\eta)\xi_2 = \partial_x\eta(\partial_x\varphi_2)_c + (\partial_y\varphi_2)_c = -\partial_t\eta + \omega_2\eta\partial_x\eta \end{cases} \quad (16)$$

we get

$$G_1(\eta)\xi_1 + G_2(\eta)\xi_2 = (\omega_2 - \omega_1)\eta\partial_x\eta. \quad (17)$$

We introduce [20], [21]

$$\xi := \rho_1\xi_1 - \rho_2\xi_2 \quad (18)$$

and hence we can write

$$(\rho_1G_2(\eta) + \rho_2G_1(\eta))\xi_2 = -G_1(\eta)\xi + \rho_1(\omega_2 - \omega_1)\eta\partial_x\eta. \quad (19)$$

Also, we introduce

$$B := \rho_1G_2(\eta) + \rho_2G_1(\eta) \quad (20)$$

and thus we can write

$$\begin{cases} \xi_1 = B^{-1}(G_2(\eta)\xi + \rho_2(\omega_2 - \omega_1)\eta\partial_x\eta) \\ \xi_2 = B^{-1}(-G_1(\eta)\xi + \rho_1(\omega_2 - \omega_1)\eta\partial_x\eta). \end{cases} \quad (21)$$

Using (17) the first 2 terms of (12) become

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}} \rho_1\xi_1 G_1(\eta)\xi_1 dx + \frac{1}{2} \int_{\mathbb{R}} \rho_2\xi_2 G_2(\eta)\xi_2 dx \\ &= \frac{1}{2} \int_{\mathbb{R}} \rho_1\xi_1 G_1(\eta)\xi_1 dx + \frac{1}{2} \int_{\mathbb{R}} \rho_2\xi_2 ((\omega_2 - \omega_1)\eta\partial_x\eta - G_1(\eta)\xi_1) dx \\ &= \frac{1}{2} \int_{\mathbb{R}} \xi G_1(\eta)\xi_1 dx + \frac{1}{2} \int_{\mathbb{R}} \rho_2(\omega_2 - \omega_1)\xi_2\eta\partial_x\eta dx, \end{aligned} \quad (22)$$

and inserting the expressions for ξ_1 and ξ_2 from (21) we obtain

$$\begin{aligned} &= \frac{1}{2} \int_{\mathbb{R}} \xi(G_1(\eta)B^{-1}G_2(\eta))\xi dx + \frac{1}{2} \int_{\mathbb{R}} \rho_2(\omega_2 - \omega_1)\xi G_1(\eta)B^{-1}\eta\partial_x\eta dx \\ &- \frac{1}{2} \int_{\mathbb{R}} \rho_2(\omega_2 - \omega_1)B^{-1}G_1(\eta)\xi\eta\partial_x\eta dx + \frac{1}{2} \int_{\mathbb{R}} \rho_1\rho_2(\omega_2 - \omega_1)^2\eta\partial_x\eta B^{-1}\eta\partial_x\eta dx. \end{aligned}$$

We can cancel the second and third terms because the operators G_1 and B are self-adjoint [22], [23], therefore

$$\begin{aligned} & \frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1)^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2)^2 dy dx \\ &= \frac{1}{2} \int_{\mathbb{R}} \xi (G_1(\eta) B^{-1} G_2(\eta)) \xi dx + \frac{1}{2} \int_{\mathbb{R}} \rho_1 \rho_2 (\omega_2 - \omega_1)^2 \eta \partial_x \eta B^{-1} \eta \partial_x \eta dx. \end{aligned} \quad (23)$$

Next, we will re-write terms 4 and 5 of (12) using the following lemma.

Lemma 1. *For a function $F(x, y)$ which is continuous over Ω with $h(x)$ defined as follows*

$$h(x) = \int_0^{\eta(x)} F(x, y) dy$$

the derivative with respect to x can be expressed as [18]

$$h'(x) = \int_0^{\eta(x)} F_x(x, y) dy + F[x, \eta] \partial_x \eta.$$

Using this lemma we let $F = y\varphi_1$ and hence

$$\int_{-h_1}^{\eta} y \partial_x \varphi_1 dy = \partial_x \left[\int_{-h_1}^{\eta} y \varphi_1 dy \right] - \xi_1 \eta \partial_x \eta. \quad (24)$$

The first term on the right-hand side is zero due to assumption (4). Similarly (noting the sign difference on the right-hand side as η is the lower limit for Ω_2)

$$\int_{\eta}^{h_2} y \partial_x \varphi_2 dy = \xi_2 \eta \partial_x \eta. \quad (25)$$

Therefore

$$\begin{aligned}
& - \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1 y \partial_x \varphi_1 dy dx - \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2 y \partial_x \varphi_2 dy dx \\
& \qquad \qquad \qquad = \int_{\mathbb{R}} (\rho_1 \omega_1 \xi_1 \eta \partial_x \eta - \rho_2 \omega_2 \xi_2 \eta \partial_x \eta) dx. \quad (26)
\end{aligned}$$

Now, inserting the expressions for ξ_1 and ξ_2 from (21) gives

$$\begin{aligned}
\rho_1 \omega_1 \xi_1 \eta \partial_x \eta - \rho_2 \omega_2 \xi_2 \eta \partial_x \eta &= \rho_1 \omega_1 B^{-1} (G_2(\eta) \xi + \rho_2 (\omega_2 - \omega_1) \eta \partial_x \eta) \eta \partial_x \eta \\
&\quad - \rho_2 \omega_2 B^{-1} (-G_1(\eta) \xi + \rho_1 (\omega_2 - \omega_1) \eta \partial_x \eta) \eta \partial_x \eta. \quad (27)
\end{aligned}$$

Expanding this out gives

$$\begin{aligned}
\rho_1 \omega_1 \xi_1 \eta \partial_x \eta - \rho_2 \omega_2 \xi_2 \eta \partial_x \eta &= \eta \partial_x \eta B^{-1} (\rho_1 \omega_1 G_2(\eta) \xi + \rho_2 \omega_2 G_1(\eta) \xi) \\
&\quad - \rho_1 \rho_2 (\omega_2 - \omega_1)^2 \eta \partial_x \eta B^{-1} \eta \partial_x \eta. \quad (28)
\end{aligned}$$

Therefore

$$\begin{aligned}
& - \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1 y \partial_x \varphi_1 dy dx - \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2 y \partial_x \varphi_2 dy dx \\
&= \int_{\mathbb{R}} \left(\eta \partial_x \eta B^{-1} (\rho_1 \omega_1 G_2(\eta) \xi + \rho_2 \omega_2 G_1(\eta) \xi) - \rho_1 \rho_2 (\omega_2 - \omega_1)^2 \eta \partial_x \eta B^{-1} \eta \partial_x \eta \right) dx. \quad (29)
\end{aligned}$$

Finally, we write the final 2 terms of (12) as

$$\frac{1}{2} \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1^2 y^2 dy dx + \frac{1}{2} \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2^2 y^2 dy dx = \frac{1}{6} \int_{\mathbb{R}} (\rho_1 \omega_1^2 - \rho_2 \omega_2^2) \eta^3 dx. \quad (30)$$

Therefore, by substituting (23), (29) and (30) into the expression for the Hamiltonian given in (12) we get the Hamiltonian of the system in terms of the conjugate variables (η, ξ) (noting the combination of the second terms in

(23) and (29))

$$\begin{aligned}
H(\eta, \xi) &= \frac{1}{2} \int_{\mathbb{R}} \xi (G_1(\eta) B^{-1} G_2(\eta)) \xi \, dx + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta^2 \, dx \\
&\quad - \frac{1}{2} \int_{\mathbb{R}} \rho_1 \rho_2 (\omega_2 - \omega_1)^2 \eta \partial_x \eta B^{-1} \eta \partial_x \eta \, dx \\
&\quad + \int_{\mathbb{R}} \eta \partial_x \eta B^{-1} (\rho_1 \omega_1 G_2(\eta) \xi + \rho_2 \omega_2 G_1(\eta) \xi) \, dx + \frac{1}{6} \int_{\mathbb{R}} (\rho_1 \omega_1^2 - \rho_2 \omega_2^2) \eta^3 \, dx.
\end{aligned} \tag{31}$$

5 Hamiltonian Equations of Motion

Using the Hamiltonian in (12) the varied Hamiltonian is given by

$$\begin{aligned}
\delta H &= \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1) \cdot \nabla \delta \varphi_1 \, dy \, dx + \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2) \cdot \nabla \delta \varphi_2 \, dy \, dx \\
&\quad + \frac{1}{2} \int_{\mathbb{R}} \rho_1 (\nabla \varphi_1)_c^2 \delta \eta \, dx - \frac{1}{2} \int_{\mathbb{R}} \rho_2 (\nabla \varphi_2)_c^2 \delta \eta \, dx + \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta \delta \eta \, dx \\
&\quad - \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1 y \delta (\partial_x \varphi_1) \, dy \, dx - \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 \omega_2 y \delta (\partial_x \varphi_2) \, dy \, dx \\
&\quad - \int_{\mathbb{R}} (\rho_1 \omega_1 \eta (\partial_x \varphi_1)_c - \rho_2 \omega_2 \eta (\partial_x \varphi_2)_c) \delta \eta \, dx + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 \omega_1^2 \eta^2 - \rho_2 \omega_2^2 \eta^2) \delta \eta \, dx.
\end{aligned} \tag{32}$$

Applying Lemma 1 to the following (Ω_1) term in the varied Hamiltonian gives

$$\begin{aligned}
& - \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 \omega_1 y \delta(\partial_x \varphi_1) dy dx \\
& = - \int_{\mathbb{R}} \partial_x \left[\int_{-h_1}^{\eta} \rho_1 \omega_1 y \delta \varphi_1 dy \right] dx + \int_{\mathbb{R}} \rho_1 \omega_1 \eta \partial_x \eta (\delta \varphi_1)_c dx. \quad (33)
\end{aligned}$$

The first term on the right-hand side is zero as $\delta \varphi_i|_{|x| \rightarrow \infty} = 0$ since $(\varphi_i)_c \rightarrow 0$ as $|x| \rightarrow \infty$ and hence, also applying Lemma 1 to the equivalent term in Ω_2 , we can write

$$\begin{aligned}
\delta H & = \int_{\mathbb{R}} \int_{-h_1}^{\eta} \rho_1 (\nabla \varphi_1) \cdot \nabla \delta \varphi_1 dy dx + \int_{\mathbb{R}} \int_{\eta}^{h_2} \rho_2 (\nabla \varphi_2) \cdot \nabla \delta \varphi_2 dy dx \\
& + \frac{1}{2} \int_{\mathbb{R}} \rho_1 (\nabla \varphi_1)_c^2 \delta \eta dx - \frac{1}{2} \int_{\mathbb{R}} \rho_2 (\nabla \varphi_2)_c^2 \delta \eta dx + \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta \delta \eta dx \\
& + \int_{\mathbb{R}} \rho_1 \omega_1 \eta \partial_x \eta (\delta \varphi_1)_c dx - \int_{\mathbb{R}} \rho_2 \omega_2 \eta \partial_x \eta (\delta \varphi_2)_c dx \\
& - \int_{\mathbb{R}} (\rho_1 \omega_1 \eta (\partial_x \varphi_1)_c - \rho_2 \omega_2 \eta (\partial_x \varphi_2)_c) \delta \eta dx + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 \omega_1^2 \eta^2 - \rho_2 \omega_2^2 \eta^2) \delta \eta dx. \quad (34)
\end{aligned}$$

Gauss' theorem is used to expand the following (Ω_1) term in terms of the interface and the upper and lower boundary normals, noting that the variation in the velocity potentials at the boundaries, $(\partial \varphi_1)_b$ and $(\partial \varphi_2)_l$, are zero:

$$\int_{\mathbb{R}} \int_{-h_1}^{\eta} (\nabla \varphi_1) \cdot \nabla \delta \varphi_1 dy dx = \int_{\mathbb{R}} ((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) (\delta \varphi_1)_c dx. \quad (35)$$

Also expanding the equivalent term in Ω_2 gives

$$\begin{aligned}
\delta H = & \int_{\mathbb{R}} \rho_1 ((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) (\delta \varphi_1)_c dx \\
& + \int_{\mathbb{R}} \rho_2 ((\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta) (\delta \varphi_2)_c dx + \frac{1}{2} \int_{\mathbb{R}} \rho_1 (\nabla \varphi_1)_c^2 \delta \eta dx \\
& - \frac{1}{2} \int_{\mathbb{R}} \rho_2 (\nabla \varphi_2)_c^2 \delta \eta dx + \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta \delta \eta dx + \int_{\mathbb{R}} \rho_1 \omega_1 \eta \partial_x \eta (\delta \varphi_1)_c dx \\
& - \int_{\mathbb{R}} \rho_2 \omega_2 \eta \partial_x \eta (\delta \varphi_2)_c dx - \int_{\mathbb{R}} (\rho_1 \omega_1 \eta (\partial_x \varphi_1)_c - \rho_2 \omega_2 \eta (\partial_x \varphi_2)_c) \delta \eta dx \\
& + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 \omega_1^2 \eta^2 - \rho_2 \omega_2^2 \eta^2) \delta \eta dx. \quad (36)
\end{aligned}$$

Next, we express the variation in the interface velocity potential as

$$\delta((\varphi_i)_c) = (\partial_y \varphi_i)_c \delta \eta + (\delta \varphi_i)_c \quad (37)$$

$$\Rightarrow (\delta \varphi_i)_c = \delta \xi_i - (\partial_y \varphi_i)_c \delta \eta, \quad (38)$$

and hence the varied Hamiltonian can therefore be written as

$$\begin{aligned}
\delta H = & \int_{\mathbb{R}} \left[-\rho_1 (\partial_y \varphi_1)_c ((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) + \rho_2 (\partial_y \varphi_2)_c ((\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta) \right. \\
& + \frac{1}{2} \rho_1 (\nabla \varphi_1)_c^2 - \frac{1}{2} \rho_2 (\nabla \varphi_2)_c^2 + (\rho_1 - \rho_2) g \eta - \rho_1 \omega_1 \eta (\partial_y \varphi_1)_c \partial_x \eta + \rho_2 \omega_2 \eta (\partial_y \varphi_2)_c \partial_x \eta \\
& \left. - \rho_1 \omega_1 \eta (\partial_x \varphi_1)_c + \rho_2 \omega_2 \eta (\partial_x \varphi_2)_c + \frac{1}{2} \rho_1 \omega_1^2 \eta^2 - \frac{1}{2} \rho_2 \omega_2^2 \eta^2 \right] \delta \eta dx \\
& + \int_{\mathbb{R}} \rho_1 \left[\omega_1 \eta \partial_x \eta + (\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta \right] \delta \xi_1 dx \\
& - \int_{\mathbb{R}} \rho_2 \left[\omega_2 \eta \partial_x \eta + (\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta \right] \delta \xi_2 dx. \quad (39)
\end{aligned}$$

Fixing ξ_1 and ξ_2 we can see that the functional derivative of the Hamiltonian with respect to the interface function, η , is

$$\begin{aligned} \delta_\eta H = & -\rho_1(\partial_y \varphi_1)_c((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) + \rho_2(\partial_y \varphi_2)_c((\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta) \\ & + \frac{1}{2}\rho_1(\nabla \varphi_1)_c^2 - \frac{1}{2}\rho_2(\nabla \varphi_2)_c^2 + (\rho_1 - \rho_2)g\eta - \rho_1\omega_1\eta(\partial_y \varphi_1)_c \partial_x \eta + \rho_2\omega_2\eta(\partial_y \varphi_2)_c \partial_x \eta \\ & - \rho_1\omega_1\eta(\partial_x \varphi_1)_c + \rho_2\omega_2\eta(\partial_x \varphi_2)_c + \frac{1}{2}\rho_1\omega_1^2\eta^2 - \frac{1}{2}\rho_2\omega_2^2\eta^2. \end{aligned} \quad (40)$$

Next, using the replacement

$$\frac{1}{2}\rho_i(\nabla \psi_i)_c^2 = \frac{1}{2}\rho_i(\nabla \varphi_i)_c^2 - \rho_i\omega_i\eta(\partial_x \varphi_i)_c + \frac{1}{2}\rho_i\omega_i^2\eta^2$$

we rewrite (40) as

$$\begin{aligned} \delta_\eta H = & -\rho_1(\partial_y \varphi_1)_c((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) + \rho_2(\partial_y \varphi_2)_c((\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta) \\ & + \frac{1}{2}\rho_1(\nabla \psi_1)_c^2 - \frac{1}{2}\rho_2(\nabla \psi_2)_c^2 + (\rho_1 - \rho_2)g\eta - \rho_1\omega_1\eta(\partial_y \varphi_1)_c \partial_x \eta + \rho_2\omega_2\eta(\partial_y \varphi_2)_c \partial_x \eta. \end{aligned} \quad (41)$$

Using the Bernoulli condition (9) we make the replacement

$$\begin{aligned} \frac{1}{2}\rho_1(\nabla \psi_1)_c^2 - \frac{1}{2}\rho_2(\nabla \psi_2)_c^2 + (\rho_1 - \rho_2)g\eta \\ = -\rho_1(\partial_t \varphi_1)_c + \rho_2(\partial_t \varphi_2)_c + \rho_1\omega_1\chi_1 - \rho_2\omega_2\chi_2 \end{aligned} \quad (42)$$

which means we can rewrite (41) as

$$\begin{aligned} \delta_\eta H = & -\rho_1(\partial_y \varphi_1)_c((\partial_y \varphi_1)_c - (\partial_x \varphi_1)_c \partial_x \eta) + \rho_2(\partial_y \varphi_2)_c((\partial_y \varphi_2)_c - (\partial_x \varphi_2)_c \partial_x \eta) \\ & - \rho_1(\partial_t \varphi_1)_c + \rho_2(\partial_t \varphi_2)_c - \rho_1\omega_1\eta(\partial_y \varphi_1)_c \partial_x \eta + \rho_2\omega_2\eta(\partial_y \varphi_2)_c \partial_x \eta + \rho_1\omega_1\chi_1 - \rho_2\omega_2\chi_2. \end{aligned} \quad (43)$$

Recalling the kinematic boundary condition in (10) and multiplying across by $(\partial_y \varphi_i)_c$ gives

$$\partial_t \eta (\partial_y \varphi_i)_c = (\partial_y \varphi_i)_c^2 - (\partial_x \varphi_i)_c (\partial_y \varphi_i)_c \partial_x \eta + \omega_i \eta (\partial_y \varphi_i)_c \partial_x \eta, \quad (44)$$

which means we can rewrite (43) as

$$\begin{aligned} \delta_\eta H = & -\rho_1 \partial_t \eta (\partial_y \varphi_1)_c + \rho_2 \partial_t \eta (\partial_y \varphi_2)_c - \rho_1 (\partial_t \varphi_1)_c + \rho_2 (\partial_t \varphi_2)_c \\ & + \rho_1 \omega_1 \chi_1 - \rho_2 \omega_2 \chi_2. \end{aligned} \quad (45)$$

From (38) we use $\partial_t \xi_i = (\partial_t \varphi_i)_c + (\partial_y \varphi_i)_c \partial_t \eta$, therefore

$$\delta_\eta H = -\rho_1 \partial_t \xi_1 + \rho_2 \partial_t \xi_2 + \rho_1 \omega_1 \chi_1 - \rho_2 \omega_2 \chi_2. \quad (46)$$

Noting that $\xi := \rho_1 \xi_1 - \rho_2 \xi_2$ this gives

$$\delta_\eta H = -\partial_t \xi + \rho_1 \omega_1 \chi_1 - \rho_2 \omega_2 \chi_2. \quad (47)$$

At the interface, using (2), we can define the velocity components in terms of the stream function for Ω_1 as

$$\begin{cases} (u_1)_c = -(\partial_y \psi_1)_c \\ (v_1)_c = (\partial_x \psi_1)_c \end{cases} \quad (48)$$

and for Ω_2 as

$$\begin{cases} (u_2)_c = -(\partial_y \psi_2)_c \\ (v_2)_c = (\partial_x \psi_2)_c. \end{cases} \quad (49)$$

However, at any moment in time any arbitrary point (x, y) at the interface will be moving at a distinct velocity which can be measured independent of knowing the vorticities or velocity potentials, i.e. $(u_1)_c = (u_2)_c$ and $(v_1)_c = (v_2)_c$, therefore

$$\begin{cases} (\partial_y \psi_1)_c = (\partial_y \psi_2)_c \\ (\partial_x \psi_1)_c = (\partial_x \psi_2)_c \end{cases} \quad (50)$$

i.e.

$$(\nabla \psi_1)_c = (\nabla \psi_2)_c \quad (51)$$

which means that $(\psi_1)_c$ and $(\psi_2)_c$ differ only by a constant. As potentials are modulo an additive constant, again using assumption (3), as $|x| \rightarrow \infty$ then χ_i goes to zero as $\chi_i = \chi_i(\eta)$ and hence $(\psi_1)_c$ and $(\psi_2)_c$ are equal, i.e.

$$\chi_1 = \chi_2, \quad (52)$$

i.e. it is a natural physical fact that there is no flow through the common interface. We define $\chi := \chi_1 = \chi_2$. Using this result, and introducing $\omega := \rho_1 \omega_1 - \rho_2 \omega_2$, (47) can be written as

$$\partial_t \xi = -\delta_\eta H + \omega \chi. \quad (53)$$

Recalling the varied Hamiltonian (39) and fixing η and using, from the kinematic boundary conditions (10),

$$\partial_t \eta = \partial_x \eta \omega_i \eta - \partial_x \eta (\partial_x \varphi_i)_c + (\partial_y \varphi_i)_c \quad (54)$$

we get

$$\delta H|_{\delta \eta=0} = \int_{\mathbb{R}} \rho_1 \partial_t \eta \delta \xi_1 dx - \int_{\mathbb{R}} \rho_2 \partial_t \eta \delta \xi_2 dx = \int_{\mathbb{R}} \partial_t \eta (\rho_1 \delta \xi_1 - \rho_2 \delta \xi_2) dx.$$

Therefore, recalling that $\xi = \rho_1 \xi_1 - \rho_2 \xi_2$ and as δ is additive $\delta \xi = \rho_1 \delta \xi_1 - \rho_2 \delta \xi_2$ this means

$$\delta H = \int_{\mathbb{R}} (-\partial_t \xi + \omega \chi) \delta \eta dx + \int_{\mathbb{R}} \partial_t \eta \delta \xi dx, \quad (55)$$

which gives the non-canonical system

$$\begin{cases} \partial_t \xi = -\delta_\eta H + \omega \chi \\ \partial_t \eta = \delta_\xi H. \end{cases} \quad (56)$$

In order to prove that this system has Hamiltonian form we first derive the following lemma.

Lemma 2.

$$\chi(x, t) = \int_{-\infty}^x \frac{\delta H}{\delta \xi(x')} dx'. \quad (57)$$

Proof. From (10)

$$\partial_t \eta = \partial_x \eta (\partial_y \psi_i)_c + (\partial_x \psi_i)_c \quad (58)$$

but, on the other hand (considering t as a parameter)

$$\frac{d}{dx} \chi(x, t) = \frac{d}{dx} \psi_i(x, \eta(x, t), t) = (\partial_x \psi_i)_c + \partial_\eta \psi_i \partial_x \eta = (\partial_x \psi_i)_c + (\partial_y \psi_i)_c \partial_x \eta. \quad (59)$$

Therefore, by comparing (58) and (59) (noting the following remark)

$$\chi(x, t) = \int_{-\infty}^x \partial_t \eta(x', t) dx'. \quad (60)$$

But, from (56)

$$\partial_t \eta(x', t) = \frac{\delta H}{\delta \xi(x')} \quad (61)$$

thus proving the lemma. \square

Remark. From the assumptions given by (3) and (4)

$$\lim_{|x| \rightarrow \infty} (\psi_i(x, y, t))_c = 0 \Rightarrow \lim_{|x| \rightarrow \infty} \chi(x, t) = 0. \quad (62)$$

Corollary 1. *From Lemma 2*

$$\int_{\mathbb{R}} \partial_t \eta(x, t) dx = 0 \quad (63)$$

and therefore

$$\int_{\mathbb{R}} \eta(x, t) dx = \text{constant}. \quad (64)$$

Remark. To calculate $\bar{\eta}$, the average of η , the above constant will be divided by an infinite length therefore $\bar{\eta} = 0$.

Therefore we can write (56) as:

$$\begin{cases} \partial_t \xi = -\delta_\eta H + \omega \int_{-\infty}^x \frac{\delta H}{\delta \xi(x')} dx' \\ \partial_t \eta = \delta_\xi H. \end{cases} \quad (65)$$

From Wahlén [17] we know that this system of equations has a Hamiltonian form

$$\begin{cases} \partial_t \xi = \{\xi, H\} \\ \partial_t \eta = \{\eta, H\} \end{cases} \quad (66)$$

where the Poisson bracket in [19] is defined as

$$\{A, B\} = \int_{\mathbb{R}} \left(\frac{\delta A}{\delta \eta(x)} \frac{\delta B}{\delta \xi(x)} - \frac{\delta A}{\delta \xi(x)} \frac{\delta B}{\delta \eta(x)} \right) dx + \omega \int_{\mathbb{R}} \left(\frac{\delta A}{\delta \xi(x)} \int_0^x \frac{\delta B}{\delta \xi(x')} dx' \right) dx. \quad (67)$$

One can verify that (67) satisfies all properties of a Poisson bracket. However, this fact will be established by other means in the next section.

6 Canonical Hamiltonian Equations of Motion

The velocity potential at the interface, ξ , is defined modulo an additive constant. We chose to transform it, as per the single media case [19], to a new variable ζ as follows

$$\xi \rightarrow \zeta = \xi - \frac{\omega}{2} \int_{-\infty}^x \eta(x', t) dx'. \quad (68)$$

We show the system under study has canonical Hamiltonian structure by the following theorem:

Theorem 1. *The system under study is a canonical Hamiltonian system described by the phase space variables η and ζ .*

Proof. From (55):

$$\delta H = \int_{\mathbb{R}} (-\partial_t \xi + \omega \chi) \delta \eta dx + \int_{\mathbb{R}} \partial_t \eta \delta \xi dx \quad (69)$$

and applying the variable transformation given by (68) gives

$$\begin{aligned} \delta H = & \\ & \int_{\mathbb{R}} \left(-\partial_t \zeta - \frac{\omega}{2} \int_{-\infty}^x \partial_t \eta(x', t) dx' + \omega \chi \right) \delta \eta(x) dx + \int_{\mathbb{R}} \partial_t \eta \left(\delta \zeta + \frac{\omega}{2} \int_{-\infty}^x \delta \eta(x') dx' \right) dx. \end{aligned} \quad (70)$$

Using Lemma 2 gives

$$\delta H = \int_{\mathbb{R}} \left(-\partial_t \zeta + \frac{\omega}{2} \chi \right) \delta \eta(x) dx + \int_{\mathbb{R}} \partial_t \eta \left(\delta \zeta + \frac{\omega}{2} \int_{-\infty}^x \delta \eta(x') dx' \right) dx. \quad (71)$$

Next, using integration by parts we can write

$$\begin{aligned} \int_{\mathbb{R}} \partial_t \eta \left(\int_{-\infty}^x \delta \eta(x') dx' \right) dx = & \left[\int_{-\infty}^x \delta \eta(x') dx' \int_{-\infty}^x \partial_t \eta(x'', t) dx'' \right]_{-\infty}^{+\infty} \\ & - \int_{\mathbb{R}} \left(\int_{-\infty}^x \partial_t \eta(x'', t) dx'' \right) \delta \eta(x) dx, \end{aligned} \quad (72)$$

and, using Corollary 1 means the first term on the right-hand side is zero and applying Lemma 2 to the second term means we rewrite (71) as

$$\delta H = \int_{\mathbb{R}} \left(-\partial_t \zeta + \frac{\omega}{2} \chi \right) \delta \eta \, dx + \int_{\mathbb{R}} \partial_t \eta \delta \zeta - \frac{\omega}{2} \int_{\mathbb{R}} \chi \delta \eta \, dx. \quad (73)$$

Noting the cancellation of the $\omega \chi$ terms this gives the canonical Hamiltonian system

$$\begin{cases} \partial_t \zeta = -\delta_\eta H \\ \partial_t \eta = \delta_\zeta H. \end{cases} \quad (74)$$

□

Thus, in general,

$$\{A, B\} = \int_{\mathbb{R}} \left(\frac{\delta A}{\delta \eta(x)} \frac{\delta B}{\delta \zeta(x)} - \frac{\delta A}{\delta \zeta(x)} \frac{\delta B}{\delta \eta(x)} \right) dx. \quad (75)$$

This indeed shows that (67) defines a (non-canonical) Poisson bracket in terms of the variables (η, ξ) .

Finally, using the transformation (68) we can write the Hamiltonian in terms of the conjugate variables (η, ζ) as

$$\begin{aligned} H(\eta, \zeta) = & \frac{1}{2} \int_{\mathbb{R}} \left[\zeta + \frac{\omega}{2} \int_{-\infty}^x \eta(x', t) \, dx' \right] (G_1(\eta) B^{-1} G_2(\eta)) \left[\zeta + \frac{\omega}{2} \int_{-\infty}^x \eta(x', t) \, dx' \right] dx \\ & + \frac{1}{2} \int_{\mathbb{R}} (\rho_1 - \rho_2) g \eta^2 \, dx - \frac{1}{2} \int_{\mathbb{R}} \rho_1 \rho_2 (\omega_2 - \omega_1)^2 \eta \partial_x \eta B^{-1} \eta \partial_x \eta \, dx \\ & + \int_{\mathbb{R}} \eta \partial_x \eta B^{-1} \left(\rho_1 \omega_1 G_2(\eta) \left[\zeta + \frac{\omega}{2} \int_{-\infty}^x \eta(x', t) \, dx' \right] \right. \\ & \left. + \rho_2 \omega_2 G_1(\eta) \left[\zeta + \frac{\omega}{2} \int_{-\infty}^x \eta(x', t) \, dx' \right] \right) dx + \frac{1}{6} \int_{\mathbb{R}} (\rho_1 \omega_1^2 - \rho_2 \omega_2^2) \eta^3 \, dx. \quad (76) \end{aligned}$$

7 Some Further Remarks

The case with periodic boundary conditions can be treated similarly to the problem with decaying to zero conditions at $\pm\infty$. The same results remain valid when all quantities take values in the class of periodic functions of period L . Then one can consider only a domain with $0 < x < L$ and replace $\int_{\mathbb{R}} dx$ with $\int_0^L dx$. (68) changes into $\zeta = \xi - \frac{\omega}{2} \int_0^x (\eta(x', t) - \bar{\eta}) dx'$ where $\bar{\eta} = \frac{1}{L} \int_0^L \eta(x, t) dx$ is the average of η . This is in order to preserve the periodicity, since the potential ξ is determined up to a constant. The details are given in [19].

8 Conclusion

A closed water-wave system consisting of 2 immiscible media with constant (non-zero) vorticities and constant densities separated by a common free interface was considered where the upper and lower media are bound above and below, respectively, by impermeable boundaries. By examining non-lateral 2-dimensional flow, with gravitationally induced waves, the system governing equations were used to derive the Hamiltonian form of the system and the equations of motion in terms of phase space variables (η, ξ) with non-canonical Hamiltonian structure. This was achieved by defining an interface velocity potential, ξ , in terms of the respective interface velocity potentials and constant densities of the 2 domains.

Moreover, by performing a variable transformation it was then shown that the system actually has canonical Hamiltonian structure with canonical phase space variables (η, ζ) . Finally, the Hamiltonian of the system in terms of these phase space variables was given.

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