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Humidity Sensor Based on a Single-mode Hetero-core Fiber Structure

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Humidity sensor based on a single-mode hetero-core fiber structure

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Using a small-core single-mode fiber (SCSMF), a novel relative humidity (RH) sensor based on an SMF28-SCSMF-SMF28 fiber structure was proposed in this paper. By depositing a humidity sensitive material, such as poly (ethylene oxide) (PEO) on the bare SCSMF fiber, the proposed structure can act as an RH sensor with high sensitivity. Experiments demonstrated that the proposed RH sensor with PEO coating can achieve a sensitivity of 430 nm per relative humidity unit (RHU) in the RH range from 80% to 83% RH and a sensitivity of 50 nm per RHU in the RH range from 83% to 95% RH. © 2011 Optical Society of America

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Monitoring and measuring relative humidity is very important in a range of areas, such as food processing, chemical manufacturing, civil engineering, weather observations, and air-conditioning control. Traditional electronic RH sensors are based on monitoring the changes in electrical conductivity or capacitance and, hence, have the disadvantage of inaccuracy due to electrical leakage, especially in a high humidity environment. Compared with electronic RH sensors, optical fiber based RH sensors offer numerous advantages, such as immunity to electromagnetic interference, small size, low weight, and remote monitoring. A wide range of RH sensing techniques based on optical fibers has been reported previously, including long period gratings (LPG) [1–3], fiber Bragg gratings [4,5], side polished fibers [6], plastic optical fibers [7], surface plasmon resonance [8,9], photonic crystal fiber interferometer [10], and tapered optical fibers [11,12]. Recently Akita proposed to use a hetero-core optical fiber as a humidity sensor, which is based on a multimode-singlemode-multimode fiber structure with the benefits of simplicity and low cost [13].

In our previous research, we have demonstrated that a single-mode-multimode-single-mode (SMS) fiber structure can act as both a temperature and displacement sensor [14,15]. If the cladding of a multimode fiber is etched away, such an SMS fiber structure can be used as a refractive index (RI) sensor [16,17]. However, etching of the fiber cladding is often complex and dangerous due to the chemicals used in the etching process. More importantly, the control of the etching process to achieve a repeatable fiber diameter is very difficult and the surface of the etched fiber is normally rough, which influences the transmission behavior of the etched fiber. In this paper, we propose to use a single-mode optical fiber with a very small core diameter instead of the multimode fiber in the SMS structure. By depositing a thin layer humidity-sensitive material, such as PEO on the surface of the fiber, the proposed structure can act as an RH sensor with high sensitivity.

The proposed RH sensor structure is shown in Fig. 1.

A conventional SMF28 fiber is used as the attaching fibers to the SCSMF. Both the SMF28 and SCSMF fibers in Fig. 1 have a step index profile. The SCSMF effectively

has four layers, if one includes the air surrounding the PEO layer. Since the core diameter of the SMF28 is much larger than that of the SCSMF, the light injected into the SCSMF from SMF28 will excite multiple modes propagating within the cladding of the SCSMF. When the RI of PEO (n_3) is less than that of the cladding (n_2), there are multiple eigenmodes transmitted within the SCSMF. Assuming the field profile within the SCSMF as $\Psi_m(r)$, the input field at the SCSMF can be written as

$$E(r, 0) = \sum_{m=1}^M b_m \Psi_m(r), \quad (1)$$

where $E(r, 0)$ is the eigenmode of the SMF28, $\Psi_m(r)$ is m th eigenmode of the step index optical fiber SCSMF, which was given by Tsao [18], and where b_m is the excitation coefficient for each mode, which can be expressed as

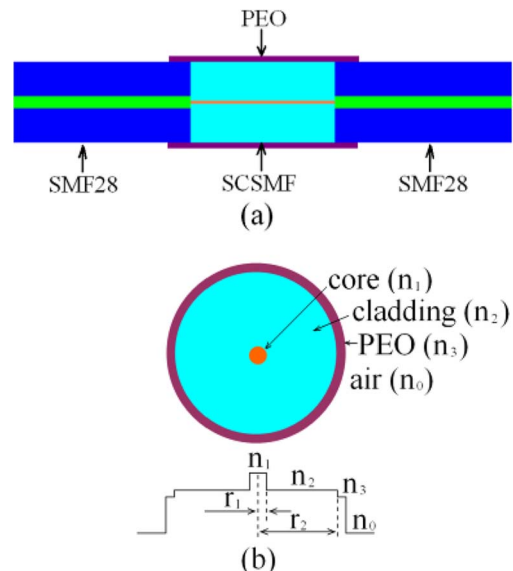


Fig. 1. SMF28-SCSMF-SMF28 fiber structure based humidity sensor. (a) View along fiber axis and (b) cross-section view of the SCSMF section.

$$b_m = \frac{\int_0^\infty E(r, 0) \Psi_m(r) r dr}{\int_0^\infty \Psi_m(r) \Psi_m(r) r dr}. \quad (2)$$

The field within the SCSMF section at a propagation distance z can thus be calculated by

$$E(r, z) = \sum_{m=1}^M b_m \Psi_m(r) \exp(j\beta_m z), \quad (3)$$

where β_m is the propagation constant of each eigenmode within the SCSMF. The transmitted power to the output SMF28 thus can be expressed as

$$L_s(z) = 10 \cdot \log_{10} \left(\frac{\left| \int_0^\infty E(r, z) E(r, 0) r dr \right|^2}{\int_0^\infty |E(r, z)|^2 r dr \int_0^\infty |E(r, 0)|^2 r dr} \right). \quad (4)$$

Simulations based on the above formula were carried out. Figure 2 gives wavelength shift versus RI of the overlay at two different overlay thicknesses. The parameters used in this simulation are $n_1 = 1.451$, $n_2 = 1.445$, $n_4 = 1$, $r_1 = 1.15 \mu\text{m}$, $r_2 = 62.5 \mu\text{m}$.

Figure 2 shows that as the RI of the overlay increases, the wavelength shift increases and the structure with a thicker overlay has a larger wavelength shift compared to that with a thinner overlay. For an RH sensor based on this structure, as the RH of the air increases, the RI of the PEO decreases, hence, the wavelength decreases. By monitoring the spectral response of the sensor, the RH can be determined, if a suitable calibration has taken place.

Experiments based on the above structure were carried out. The SMF28 fiber is a conventional fiber used in optical communications and supplied by Corning. The SCSMF fiber has core and cladding refractive indices of 1.467 and 1.461, respectively, at 532 nm with mode field diameter of $3.5 \pm 0.5 \mu\text{m}$ at 515 nm. The SMF28-SCSMF-SMF28 fiber structure was fabricated by fusion splicing. The coating of the SCSMF was fully stripped and the length of the SCSMF section was 40 mm, which was carefully selected to achieve a relatively narrow bandwidth and a compact sensor length. The humidity sensing material used in this experiment is PEO, which

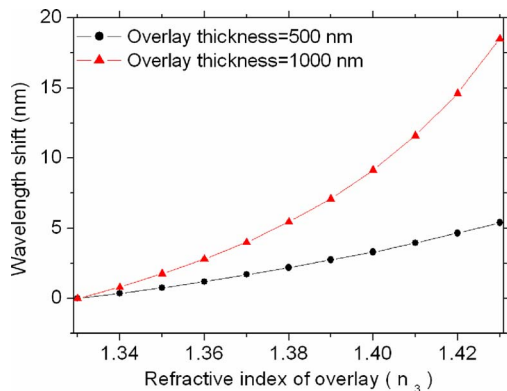


Fig. 2. Simulated wavelength shift versus RI of the overlay.

has an RI of 1.4539 at the wavelength of 589.3 nm. The PEO solution containing 10 wt.% was prepared by mixing PEO and deionized water. The PEO was then deposited by passing the SCSMF section through a drop of the PEO solution using a motor controlled translation stage. By changing the translation speed, coatings with different thicknesses can be achieved. In our experiments two samples were prepared with two different translation speeds: 4 mm/s (marked as sensor 1) and 10 mm/s (marked as sensor 2). It should be noted that due to limitations of the experimental equipment, the thickness of the coating could not be exactly measured. However, under observation using a microscope with 600 \times magnifications, it is concluded that the coating thickness for both samples is less than 1 μm and that the coating of sensor two is seen to be thicker than that of sensor one. Optimal coating thickness could be achieved by dynamic monitoring of spectral response of the SMF28-SCSMF-SMF28 fiber structure.

The sensors were then placed in a climate control chamber. Light from a broadband optical source was injected into the sensor and the output signal was monitored using an optical spectrum analyzer (OSA). The humidity within the chamber was first increased to 95% RH, and then was decreased gradually to 40% RH with steps of 0.1% RH (maximum available resolution of the setup) at a fixed temperature of $19.2 \pm 0.5 \text{ }^\circ\text{C}$. The spectral responses of the two sensors at different RH values are shown in Fig. 3.

Figure 3 shows that as the RH increases, the central wavelength of the spectral response increases for both sensors. This is due to the fact that as RH decreases, the RI of the PEO increases, and, hence, the eigenmodes excited in the SCSMF section change resulting in the changes to the light coupled to the output SMF28. Figure 3 also shows that as the RH decreases, the bandwidth of the spectra increases and the spectra shape becomes irregular, especially for sensor two. This could possibly be explained as water vapor diffusion inside the PEO introducing complex changes to the polymer material, such as optical density, RI, and surface morphology [2].

For sensor one the range of the central wavelength shift was more than 20 nm when the RH decreased from 95% RH to 40% RH, while for sensor two this value was almost two times larger. This indicates that sensor two

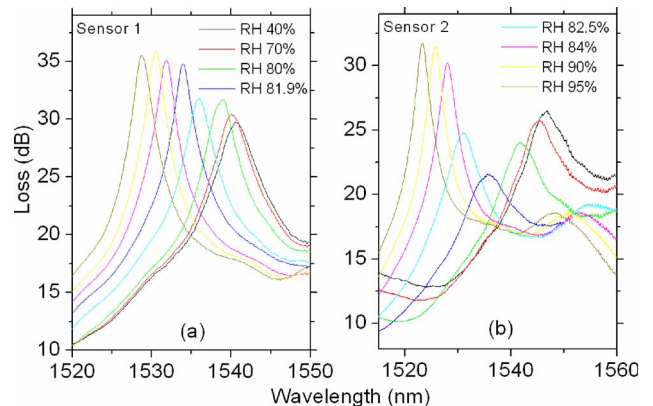


Fig. 3. Spectral responses of (a) sensor one and (b) sensor two at different RH values.

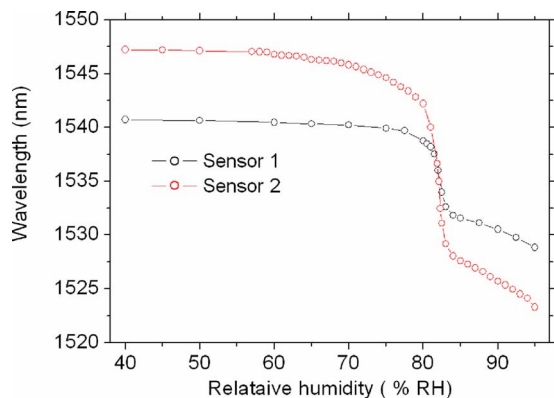


Fig. 4. Resonant wavelength shift of the SMF28-SCSMF-SMF28 fiber structure based RH sensor versus different RH values.

has a higher sensitivity than sensor one. Figure 4 shows the measured central wavelength variations versus RH. It is noted that in this study, the central wavelength is the 3 dB mean wavelength measured by the OSA, which is a more reliable measurement compared to the peak central wavelength.

Figure 4 shows that for both sensors, as RH increases from 40% RH to 95% RH, the central wavelength of the response shifts to a shorter wavelength. For sensor one, there is no significant wavelength shift in the range of RH from 40% to 70% RH; when the RH is higher than 70%, the wavelength shift is significant, especially in the range from 80% to 83% RH where it is equal to 6 nm. In the RH range from 83% RH to 95% RH, there is a circa 4 nm wavelength shift. The total wavelength shift in the RH range from 40% RH to 95% RH for sensor one is circa 12 nm. Sensor two shows a similar wavelength shift behavior but with a larger wavelength shift value (24 nm) in the RH range from 40% to 95% RH, indicating that sensor two has higher sensitivity than sensor one, from which it is possible to conclude that the thickness of the PEO layer has an effect on the sensor sensitivity. Assuming the OSA has a wavelength resolution of 0.01 nm, the proposed sensors have humidity resolutions of 0.005% RH and 0.0023% RH in the RH range from 80% RH to 83% RH, and resolutions of 0.03% RH and 0.02% RH in the RH range from 83% to 95% RH for sensor one and two, respectively. By comparison with an LPG humidity sensor coated with a similar humidity sensing material of PEO/CoCl₂, which has a maximum wavelength shift of 7.5 nm at RH range from 77% to 95%, the sensor two used in our experiment has a higher sensitivity with a wavelength shift of 20.5 nm in the same RH range.

In conclusion, we have proposed an RH sensor based on an SMF28-SCSMF-SMF28 fiber structure. Compared

to the existing optical fiber based RH sensors, the RH sensor proposed in this paper has the advantages of high resolution, low cost, and ease of fabrication.

It should be noted that in this paper we have carried out experiments for RH values less than 95% RH due to the fact that PEO dissolves if the humidity is higher than 95% RH, which could result in damage to the sensor. However, if a different humidity-sensitive material is used as a coating, for example, hydrogel [1], which is stable in a high humidity range up to 100%, then this SMF28-SCSMF-SMF28 fiber structure based RH sensor can be used to measure RH values up to 100% RH.

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