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2010-11-11

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Recommended Citation

Murphy, J., Boyle, F.: A Numerical Methodology to Fully Elucidate the Altered Wall Shear Stress in a Stented Coronary Artery. Cardiovascular Engineering and Technology,Vol. 1, Number 4, pp256-268. 2010. doi:10.1007/s13239-010-0028-0

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Funder: Department of Mechanical Engineering, Technological University Dublin (DIT) and the Irish Research Council for Science Engineering and Technology (IRCSET)

A Numerical Methodology to Fully Elucidate the Altered Wall Shear **Stress in a Stented Coronary Artery**

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(Received 29 May 2010; accepted 26 October 2010)

Associate Editor John M. Tarbell oversaw the review of this article.

Abstract-Arterial restenosis after coronary stenting is 10 caused by excessive tissue growth which is stimulated by arterial injury and alterations to the hemodynamic wall shear 12 stress (WSS). Recent numerical studies have predicted only minor differences in the altered WSS between different stent designs using a commonly employed threshold assessment technique. While it is possible that there are only minor 16 differences, it is more likely that this assessment technique is incapable of fully elucidating the alterations to the WSS 18 created by stent implantation. This paper proposes a methodology that involves a more complete investigation 20 into the stent-induced alterations of WSS by incorporating the full suite of WSS-based variables: WSS, WSS gradient (WSSG), WSS angle gradient (WSSAG) and oscillatory shear index (OSI). The four variables are analyzed quantitatively and qualitatively to assess the effect of the stent implantation. The methodology is applied to three stents with contrasting designs: the Palmaz Schatz (PS), Gianturco Roubin II (GR-II) and Bx-Velocity (Bx) stents. For WSS the methodology ranks the stents (best to worst) as follows: PS, GR-II, Bx (Cohen's d: -0.01, -0.613), for WSSG: PS, Bx, 30 GR-II (d: 0.159, 0.764), for WSSAG: PS GR-II Bx (d: 0.213, 0.082), and for OSI: PS, GR-II, Bx (d: 0.315, 0.380). The suggested quantitative and qualitative assessment of the WSS-based variables is shown to improve upon, and 34 highlight the weakness of, the previously used threshold 35 assessment technique. The proposed methodology could be 36 utilized to minimize WSS alterations at the design stage of future coronary stents.

38 Keywords-Pulsatile flow, Restenosis, Multi-variable analy-39 sis.

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INTRODUCTION

43 Balloon angioplasty is a minimally invasive inter-44 ventional technique to restore blood flow through 45 coronary arteries constricted by atherosclerosis. However, a subsequent re-blockage or restenosis can 46 occur if the artery elastically recoils back to its nar-47 rowed state. Bare metal stents (BMSs) were introduced 48 to prevent this arterial recoil but restenosis remains a 49 significant problem with BMSs occurring in between 50 10 and 50% of patients treated.^{12,17} Restenosis in 51 stented arteries is essentially caused by the excessive 52 growth of new tissue in the stented segment of the 53 artery, a process termed intimal hyperplasia (IH). 54 Currently, the implantation of drug-eluting stents 55 (DESs) has proven effective in reducing restenosis rates 56 to below 10%.8,31 57

In a clinical study,¹⁷ stent design was found to be 58 the second strongest risk factor, after vessel size, for 59 restenosis at six-month follow-up angiography among 60 3370 patients. Stent-design-related stimuli for reste-61 nosis are arterial injury and altered hemodynamics. 62 The influence of stent design on arterial injury has been 63 demonstrated³⁸ and the severity of the injury corre-64 lated to the volume of subsequent tissue growth.^{38,39} 65 Altering the hemodynamic wall shear stress (WSS) at 66 the artery wall through stent implantation has also 67 been shown to influence arterial tissue growth.^{14,26} 68 Previous works^{5,22,30} which have linked altered hemo-69 dynamics to stent design prompted further investiga-70 tions into the hemodynamic environment of the 71 stented artery. 72

Currently, state-of-the-art numerical investigations 73 into WSS in the stented artery employ three-74 dimensional (3D) and transient computational fluid dynamics (CFD).^{3,4,6,10,11,15,21,23,25,37} In these studies 75 76 the alteration of the WSS acting on the wall is some-77 times analyzed using threshold values of the WSS 78 79 $(WSS < 0.5 \text{ N/m}^2)$ and WSS gradient (WSSG >200 N/m^3) as tissue growth has been found to be more 80 prolific in areas where the WSS and WSSG are lower 81 and higher than these thresholds, respectively.^{18,20} One 82 such study²³ examined the effect of stent foreshortening 83

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84 on WSS, and found that for 0, 12, and 25% foreshortening there was 71, 77, and 78% of the stented 85 area with WSS $< 0.5 \text{ N/m}^2$ and 54, 50, and 54% of the 86 87 stented area with WSSG > 200 N/m³, respectively. In 88 a more recent study,³ CFD analyzes of four commer-89 cially available BMSs were conducted. Comparisons 90 between two of the stents with contrasting design, the 91 Bx-Velocity stent (Cordis Corp., Miami, FL, USA) 92 and the Jostent Flex (JOMED AB, Helsingborg, 93 Sweden), showed 58 and 57% of the stented area with WSS $< 0.5 \text{ N/m}^2$ respectively. The effect of strut 94 95 thickness on WSS was also examined using Jostent 96 Flex stents with strut thicknesses of 0.05 and 0.15 mm. The thinner struts led to 61% of the stented area with 98 WSS $< 0.5 \text{ N/m}^2$ compared with 57% for the thicker 99 struts. Duraiswamy et al.¹¹ also conducted CFD ana-100 lyzes of three, second-generation, commercially available BMSs: the Bx-Velocity stent, the Aurora stent (Medtronic, Inc., Minneapolis, MN, USA) and the 103 NIR stent (Boston-Scientific Corp., Natick, MA, 104 USA). They found 59, 57, and 59% of the stented area 105 with WSS $< 0.5 \text{ N/m}^2$ and 75, 83, and 88% of the stented area with WSSG > 200 N/m^3 for the 106 Bx-Velocity, Aurora and NIR stents, respectively. 107

108 These previous studies depict only minor differences in the altered WSS between stent designs. However, 109 numerous studies have shown that stent strut angle,²⁶ 110 111 strut thickness^{16,35} and strut configuration^{17,27,38} have a significant influence on the arterial response to stent 112 implantation. In light of this, it is highly probable that 113 114 using threshold values of only the WSS and WSSG 115 variables is not sufficient to fully elucidate stent-116 induced alterations in arterial WSS.

In this work, a numerical prediction methodology is 117 118 proposed which utilizes the two commonly used vari-119 ables (i.e., WSS and WSSG) plus two additional WSS-120 based variables, the WSS angle gradient (WSSAG) and 121 the oscillatory shear index (OSI). Each of these vari-122 ables highlights a different type of alteration to the 123 arterial WSS which could lead to IH. Instead of using 124 threshold values, statistical measures of the full dis-125 tribution of each of these variables are calculated for a 126 more complete analysis. To demonstrate the method-127 ology, it is applied to three stents with contrasting 128 features. The stents are then ranked based on the sta-129 tistical measures. Comparisons are made between the 130 results from the analyzes and the two-variable thresh-131 old analysis described above. The proposed method-132 ology can be used to identify areas of altered arterial 133 WSS at the design stage of future bare metal, as well as 134 permanent and bioabsorbable drug-eluting coronary 135 stents.

136 The paper is laid out as follows: "Materials and 137 Methods" section describes the proposed methodology 138 which includes the generation of the computational domain, the CFD analysis and the post-processing. 139 The results from the application of the methodology to 140three stents are presented in "Results" section, with the 141 conclusions given in "Discussion" section. 142

MATERIALS AND METHODS 143

The methodology begins with the generation of a 144 geometric model of the 3D lumen of the stented artery. 145 This model is discretized and used as the computa-146 tional domain for the CFD analysis. The WSS vectors 147 are predicted on domain surfaces that represent living 148 tissue. These vectors are then post-processed to pro-149 duce the magnitudes of the four WSS-based variables: 150 WSS, WSSG, WSSAG and OSI. The distribution of 151 these variables is then analyzed using quantitative and 152 qualitative statistical methods. 153

Generation of the Computational Domain 154

A 3D geometric model is first created beginning 155 with a solid cylinder measuring the length and external 156 diameter of the stent, from which the geometry of the 157 complete stent is removed. This represents full strut 158 exposure to the blood flow. The geometric model is 159 then extended proximal and distal to the stented sec-160 tion by adding cylinders with lengths equal to the 161 entrance length for fully-developed laminar flow in a 162 circular pipe and with diameters which create a stent-163 to-artery deployment ratio of 1.09:1 similar to a nor-164 mal in vivo value.²⁷ This ratio is defined as the inner 165 diameter of the deployed stent to the inner diameter of 166 the unstented artery. Finally, a novel methodology to 167 numerically predict tissue prolapse between stent 168 struts³² is employed. Briefly, the prolapsing tissue 169 creates a variable arterial radius r given by 170

$$\frac{r}{R_0} = 1 - \frac{x\delta}{2R_0} \left\{ 1 + \cos\frac{2\pi}{L} \left(z - \frac{L}{2}\right) \right\}$$
(1)

172 along the spatial coordinate z between two stent struts, where R_0 is the external diameter of the stent, L is the 173 distance between the stent struts, δ is the prolapse 174 depth and $\delta = CL$ where C is the coefficient of pro-175 lapse derived from finite element analysis (FEA) 176 data.³⁶ The prolapse reduction factor x is initiated at a 177 distance of 0.5L from struts offering additional scaf-178 folding support as shown in Fig. 1. The prolapse 179 reduction factor linearly decreases the prolapse to zero 180 at the stent strut providing the additional support. The 181 prolapsing tissue is then removed from the geometric 182 model. The geometric model thus created is discretized 183 using an unstructured mesh topology comprising of 184 4-node tetrahedral elements to form the computa-185 tional domain. Several simulations are performed to 186

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187 investigate the effect of mesh density to ensure mesh-188 independent results are obtained. This methodology is 189 applied to stents closely resembling the Palmaz Schatz 190 (PS) stent (Johnson and Johnson Interventional System, 191 Warren, NJ, USA), the Gianturco Roubin II (GR-II) 192 stent (Cook Inc., Bloomington, IN, USA) and the 193 Cordis Bx-Velocity (Bx) stent (Johnson and Johnson 194 Interventional System, Warren, NJ, USA) all implanted 195 in the left-anterior-descending (LAD) coronary artery 196 (Fig. 2). These contrasting stent designs are chosen 197 specifically to identify the effects of the different geo-198 metric features on the WSS. Also, the prior knowledge 199 of the in vivo performance of these stents is useful when 200 analyzing the results as the altered hemodynamics may 201 have contributed to their restenosis rates.

Details of the 3D geometric models are provided in Table 1. The unstented sections of the artery are 3.2 mm in diameter and 21.3 mm in length. Meshindependent results are achieved with 4,551,484 elements for the PS stent, 3,038,536 elements for the GR-II stent and 5,840,890 elements for the Bx stent.



FIGURE 1. Illustration of the primary and secondary scaffolding direction of part of the PS stent. The arterial tissue protrudes a depth δ into the stented artery and is supported in the primary scaffolding direction and partially supported (shaded section) in the secondary scaffolding direction. On the stent struts, the meshes have a maximum ele-208 ment edge length of 20–30 μ m depending on the stent 209 and a minimum edge length of 1 μ m for all stents to 210 allow adequate resolution of any complex geometric 211 features. Elements in the center of the artery have a 212 maximum edge length of 200 μ m. Mesh independence 213 is based on a less than 4% change in the RMS value of 214 the magnitudes of WSS vectors between successive 215 meshes along sample lines in the domain, an example 216 of which is shown in Fig. 3a. 217

The general form of the governing flow equations219for the conservation of mass and momentum are given220in vector form in Eqs. (2) and (3), respectively:221

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \left(\rho \vec{V} \right) = 0 \tag{2}$$

$$\frac{\rho\vec{V}}{\partial t} + \vec{\nabla} \cdot \left(\rho\vec{V}\otimes\vec{V}\right) = -\vec{\nabla}p + \vec{\nabla} \cdot \left(\vec{\tau}_{ij}\right)$$
(3)

where ρ is the fluid density, p is the static pressure and \vec{V} is the velocity vector. In this work, the blood flow in 226



FIGURE 2. Geometric models of the LAD arteries implanted with the PS stent (left), the GR-II stent (middle) and the Bx stent (right).

/	TABLE 1.	Geometric characteristics of the stent models.	

Geometric characteristic	Palmaz Schatz	Gianturco Roubin II	Bx-Velocity
Length (mm)	14.3	20.0	12.5
Internal diameter (mm)	3.5	3.5	3.5
Strut thickness \times width (mm)	0.0635 × 0.152	0.076 × 0.172	0.14 × 0.13
Stent total surface area (mm ²)	108.92	83.84	100.31
Prolapsing tissue volume (mm ³)	5.71	15.12	6.52
Normalized prolapsing tissue volume (mm ³ /mm)	0.40	0.76	0.52
Stent to tissue contact area (mm ²)	44.71	30.91	23.69
Normalized stent to tissue contact area (mm ² /mm)	3.13	1.55	1.90

Certain values are normalized by the stent length.

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FIGURE 3. (a) Magnitude of WSS along a sample line in the model of the LAD coronary artery implanted with a GR-II stent for three successive mesh densities and (b) average velocity applied at the inlet to simulate basal flow in the LAD coronary artery.

227 the stented artery is assumed time-dependent, laminar 228 and incompressible. With these assumptions the vis-229 cous stress tensor $\vec{\tau}_{ij}$ is given by

$$\vec{\tau}_{ij} = \mu \left(\ \vec{\nabla} \vec{V} + \ \vec{\nabla} \vec{V}^{\mathrm{T}} \right) \tag{4}$$

231 where μ is the fluid dynamic viscosity, which is a 232 function of the shear rate. The governing equations are 233 solved by the commercial software package ANSYS 234 CFX Version 12 (Canonsburg, PA, USA) in a Carte-235 sian coordinate system using a vertex-centered finite-236 volume scheme with implicit time-stepping, a scheme 237 which is second-order accurate in both space and time.

238 A transient, fully-developed, laminar, axial-velocity-239 profile is applied at the inlet of the computational 240 domain which corresponds to the desired blood flow 241 conditions in the coronary artery. A fixed static pres-242 sure equal to the reference pressure of 114600 Pa is 243 applied at the outlet of the domain. This pressure 244 represents the mean arterial blood pressure in the LAD 245 coronary artery. The no-slip boundary condition is 246 applied on all surfaces representative of the artery wall 247 and the stent struts. The blood density is assumed 248 constant with a value of 1050 kg/m³. The non-249 Newtonian nature of the flow is accommodated using 250 the Carreau model written

$$\mu = \mu_{\infty} + (\mu_0 - \mu_{\infty}) \left[1 + (\gamma \lambda)^2 \right]^{\left(\frac{q-1}{2}\right)}$$
(5)

where γ is the shear rate calculated as the second invariant of the strain rate tensor and the constants are

$$\mu_0 = 0.056 \text{ Ns/m}^2 \quad \lambda = 3.31 \text{ s}$$

$$\mu_{\infty} = 0.00345 \text{ Ns/m}^2 \quad q = 0.375 \qquad (6)$$

256 At each timestep the convergence criterion 257 employed is a 10^{-5} reduction in the maximum residuals

of the discretized equations. Simulations are run for
three cardiac cycles to ensure periodic convergence of
investigate the effect of the timestep so as to ensure
temporal convergence is achieved.258
259259
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The flow rate chosen corresponds to fully-developed 263 pulsatile basal flow conditions in the human LAD 264 coronary artery³³ and is shown in Fig. 3b. The average 265 Reynolds number for the cycle is 111 and the average 266 flow rate is 55 mL/min. The period of the cardiac cycle 267 is 0.8 s, and the simulation is run for three consecutive 268 cycles with a timestep of 12.5 ms. This timestep is 269 sufficient to ensure temporal convergence is achieved. 270 Computations are performed on a HP xw6400 64-bit 271 workstation using two processors of a quad Intel 272(Xeon) 2 GHz CPU and 6 GB of RAM. 273

Post-Processing 274

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The vertex-centered finite-volume scheme employed 275 by ANSYS CFX calculates the variables at the vertices 276 of the elements. All post-processing to calculate the 277 WSS-based variables is then conducted in Tecplot 360 278 2008 (Bellevue, WA, USA). The WSS, WSSG, and 279 components of the WSSAG and OSI are calculated at 280 each timestep of the third cycle and are then time-281 averaged over this cycle using the trapezoidal method 282 of numerical integration. The calculation of these 283 variables is described below. 284

Wall Shear Stress 285

Lower than physiologic values of WSS (<1.5 N/m²) 286 can cause dysfunction of the endothelial cells (ECs) 287 which line the artery. Under such conditions, ECs 288 act as a catalyst for IH through, for example, the 289 Author Proof

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290 upregulation of tissue growth factors such as PDGF-A and PDGF-B.^{29,45} Numerous studies which incorpo-291 rate numerical and experimental results have corre-292 lated areas of low WSS with increased IH.^{26,43,46,47} 293

294 The dot product of the unit normal vector \vec{l} to a 295 surface and the viscous stress tensor denoted $\vec{\tau}_{ii}$ yields 296 the WSS, i.e.,

$$\vec{l} \cdot \vec{\tau}_{ij} = \vec{\tau}_{w_{xyz}} = \tau_{w,x} \vec{i} + \tau_{w,y} \vec{j} + \tau_{w,z} \vec{k}$$
(7)

298 where $\tau_{w,x}$, $\tau_{w,y}$ and $\tau_{w,z}$ are the Cartesian components of the WSS vector in the x, y and z directions, 299 respectively. The magnitude of the WSS vector is cal-300 301 culated as

WSS =
$$\left(\tau_{w,x}^2 + \tau_{w,y}^2 + \tau_{w,z}^2\right)^{1/2}$$
 (8)

Wall Shear Stress Gradient

305 ECs which line the artery are often denuded by the 306 stenting procedure and must be replaced to prevent IH.^{7,41} However, *in vitro* studies show that bovine ECs 307 migrate away from areas of high WSSG with magni-308 tudes above 5000 N/m³⁹ and 3400 N/m^{3.42} As such, 309 310 there are likely to be less ECs in areas of high WSSG in the stented artery. In computational studies, sites that 311 312 are susceptible to IH have been correlated with sites where the WSSG has been predicted to exceed 200 N/m^3 313 in an end to side anastomosis model^{20,34} and a rabbit 314 315 iliac model.²⁶

316 The WSSG is a measure of the spatial rate of change 317 of the WSS vector and in a local coordinate system is 318 calculated as

WSSG =
$$\left[\left(\frac{\partial \tau_{w,m}}{\partial m} \right)^2 + \left(\frac{\partial \tau_{w,n}}{\partial n} \right)^2 \right]^{1/2}$$
 (9)

320 where m is the WSS direction and n is the direction tangential to the arterial surface and normal to m. The 321 322 WSSG is calculated locally at each node using least 323 squares fitting with singular value decomposition to 324 find the "best fit" for the gradient components from 325 the data at the surrounding nodes.

Wall Shear Stress Angle Gradient 326

ECs align with the flow direction creating a selective 327 328 barrier to blood borne particles such as inflammatory cells.²⁹ Sudden directional changes in the WSS may 329 lead to abnormal stresses on the junctions between 330 331 these barrier cells resulting in increased permeability and risk of inflammation, a precursor of IH.44 The 332 333 WSSAG vector has been suggested as a meshindependent variable to quantify these directional 334 changes.²⁸ 335

The magnitude of the WSSAG is calculated as 336

WSSAG =
$$\left(\left(\frac{\partial \phi}{\partial m} \right)^2 + \left(\frac{\partial \phi}{\partial n} \right)^2 \right)^{1/2}$$
 (10)

where ϕ is the angular difference between the time-338 averaged WSS vector at the node of interest $\vec{\tau}_0$ and the 339 corresponding vector at the neighbor node $\vec{\tau}_r$ and is 340 computed as 341

$$\phi = \pm \cos^{-1} \left(\frac{\vec{\tau}_0 \cdot \vec{\tau}_r}{|\vec{\tau}_0| |\vec{\tau}_r|} \right), \quad -\pi < \phi \le \pi$$
(11)

for each of the neighbor nodes. At the node of interest 343 the value of ϕ is set to zero and the WSSAG is 344 calculated using a similar method to the WSSG cal-345 culation. The WSSAG thus calculated is mesh depen-346 dent only at points of boundary layer separation and 347 reattachment in the flow, with values tending toward 348 infinity as the mesh spacing reduces to zero. To prevent 349 these flow features from affecting the WSSAG, an 350 upper limit of 300 rad/mm is set on the variable. This 351 approximately corresponds to the WSSAG magnitude 352 created by the maximum angular difference between 353 two WSS vectors (π) acting on two small (~10 μ m) 354 adjacent ECs. 355

Oscillatory Shear Index 356

Time-dependent directional changes in the WSS 357 may also lead to endothelial dysfunction. Specifically, 358 areas of oscillating WSS have been shown to correlate 359 with atherosclerotic plaque location.¹⁹ Transient 360 directional changes in WSS are quantified by the 361 oscillatory shear index (OSI). It is possible that areas 362 of high OSI in the stented artery increase the risk of IH 363 through endothelial dysfunction. 364 365

The OSI is calculated as

 $\mathbf{OSI} = 1 - \frac{\left| \int_{0}^{T} \vec{\tau}_{w} dt \right|}{\int_{0}^{T} |\vec{\tau}_{w}| dt}$ (12)

where T is the period of the cardiac cycle. The range 367 of this variable is from 0 for unidirectional flow, to 368 a maximum of 1 in areas of highly-altered fully-369 oscillatory WSS. 370

Analysis of Results 371

The WSS, WSSG, WSSAG and OSI variables, ini-372 tially calculated at the element vertices, are finally face-373 averaged for analysis. The area distribution of these 374 375 face-averaged variables is visualized using histograms by displaying the amount of area contained between 376 377 specific intervals of the variable value. In addition to

this qualitative technique, the area-averaged mean,
standard deviation, and kurtosis of the distribution of
each variable are also calculated for quantitative
analysis. The area-averaged mean is calculated as

$$\mu = \frac{\sum_{j=1}^{e} \left(A_j \times \phi_j\right)}{\sum_{j=1}^{e} A_j}$$
(13)

383 where ϕ_j is the face-averaged variable value at the face 384 *j*, A_j is the surface area of the face *j* and the summation 385 is over e mesh faces. A high mean is desirable for the 386 WSS, whereas a low mean is desirable for the WSSG, 387 WSSAG and OSI. The area-averaged standard devia-388 tion of the distribution is calculated as

$$\sigma = \sqrt{\frac{\sum\limits_{j=1}^{e} \left[\left(A_{j} \right) \times \left(\phi_{j} - \mu \right)^{2} \right]}{\sum\limits_{j=1}^{e} A_{j}}}$$
(14)

390 where the terms are as before. The standard deviation 391 provides a measure of the typical difference between 392 variable values and the mean value of the distribution. 393 Low values of standard deviation signify that the mean 394 is a better representation of values everywhere on the 395 artery wall. However, the standard deviation can be 396 heavily influenced by extreme variable values far from 397 the mean. The kurtosis, calculated as

$$K = \frac{\sum_{j=1}^{e} \left[\left(A_j \right) \times \left(\phi_j - \mu \right)^4 \right]}{\sum_{j=1}^{e} \left(A_j \times \sigma^4 \right)}$$
(15)

provides a measure of how heavily influenced the
standard deviation is by extreme values in the distribution. A mean value may still be a good representation of the variable values everywhere in the artery
even though the standard deviation is high, as long as
the kurtosis is also high.

405 For each variable, the distributions associated with
406 each stent are compared using Cohen's *d* which mea407 sures the standardized difference between the magni408 tudes of the distributions. Comparing stent A to stent
409 B, Cohen's *d* is calculated as

$$d = \frac{\mu_{\text{stent B}} - \mu_{\text{stent A}}}{\sigma_{\text{pooled}}}$$
(16)

411 where

$$\sigma_{\text{pooled}} = \sqrt{\left(\frac{\sigma_{\text{stent A}} + \sigma_{\text{stent B}}}{2}\right)^2} \tag{17}$$

For WSS, negative d values are produced if stent A is the better stent and conversely for WSSG, WSSAG and OSI, positive d values favor stent A. The value of d indicates the difference between the performances of the stents with regard to each variable. 418

RESULTS

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Results are displayed in histograms for all four 420 WSS-based variables. Logarithmic scales are used 421 where appropriate to display all the relevant informa-422 tion. The area in the histograms is normalized by the 423 total area analyzed which is the tissue area confined 424 within the axial limits of the stent. Contour plots of the 425 WSS, WSSG, WSSAG and OSI are presented in Fig. 4 426 for visualization. Illustrations of WSS vectors and the 427 computational mesh near a Bx strut are shown in 428 Figs. 5a and 5b, respectively. 429



FIGURE 4. Contour plots of the WSS, WSSG, WSSAG and OSI predicted on the artery wall after implantation of the coronary stents.



FIGURE 5. (a) WSS vectors in the vicinity of an S-connector of the Bx stent and (b) a view of the surface mesh of the uneven prolapse tissue around the same S-connector.



FIGURE 6. Distributions of the WSS. The bars represent the amount of normalized area with WSS values bounded by the tick marks on the abscissa. Bin widths are 0.05 N/m^2 .

Wall Shear Stress

431 The distribution of the WSS is presented in Fig. 6 432 for the three stents. Mean WSS values are similar for the PS and GR-II stents with values of 0.760 and 433 0.764 N/m^2 , respectively. The mean is substantially 434 lower for the Bx stent with a value of 0.522 N/m^2 . 435 436 These WSS values are 25-50% lower than those 437 expected for an unstented 3.2 mm artery under similar 438 flow conditions ($\sim 1.0 \text{ N/m}^2$). The results therefore 439 predict that insertion of these stents reduces the WSS 440 on the artery wall. Figure 4 shows that WSS values are reduced below 1.0 N/m² in large areas around all stent 441 442 struts. This is a similar result to previous studies.^{23,24} 443 The standard deviation of the WSS is slightly higher for the GR-II stent, and the relatively low kurtosis 444 reveals this is not due to extreme values but rather a 445 wider spread of WSS values in the artery. The 63% 446 higher value of kurtosis for the PS stent compared to 447 the GR-II stent indicates that the PS mean WSS value 448 449 represents a larger portion of the artery compared to the similar GR-II mean value. As such, conditions are 450 more favorable in the artery implanted with the PS 451 stent compared to the GR-II stent, with the worst WSS 452 values created by implantation of the Bx stent. Large 453 areas of low WSS are visible on the proximal side of 454 the GR-II struts in Fig. 4, due to low flow velocity in 455 this region. The thicker struts of the Bx stent have a 456 notable effect on the near-strut low WSS region which 457

458 is considerably larger than that for the similarly shaped 459 PS stent. Comparing the stents gives PS to Bx 460 (d = -0.703), PS to GR-II (d = -0.010) and GR-II to 461 Bx (d = -0.613). This puts the stents in order from 462 best to worst as PS, GR-II and Bx.

The commonly used threshold method of analysis 463 shows that the PS stent has 22.4% of arterial tissue 464 exposed to WSS $< 0.5 \text{ N/m}^2$ compared with 32.3% for 465 the GR-II stent and 49.5% for the Bx stent. In this 466 case, through comparison with the proposed method-467 468 ology, the threshold method is capable of identifying 469 the alterations to the magnitude of the WSS after 470 implantation of these particular stents.

Wall Shear Stress Gradient

472 The distribution of the WSSG is shown in Fig. 7. The GR-II stent has the highest mean value, followed 473 by the Bx stent and finally the PS stent. Further 474 475 examination of the results reveals the highest standard 476 deviation and lowest kurtosis for the GR-II stent 477 indicating a wider spread of WSSG values leading to 478 more area subjected to higher magnitudes of WSSG. 479 Comparing the PS and Bx stents, the distributions of 480 WSSG in the artery are similar. The slightly lower 481 mean and higher kurtosis marginally favors the PS as 482 the stent with the best WSSG conditions. Figure 4 483 reveals the areas of highest WSSG at the articulation 484 site and also proximal and distal to the struts that 485 traverse the flow with the PS stent. High values of WSSG (>2000 N/m³) are visible along the length of 486 487 the GR-II stent. The high WSSG values are located 488 on the surfaces of the unsupported tissue that is pro-489 lapsing into the artery. Uneven prolapse near the

S-connectors of the Bx stent has also produced high 490 WSSG values. Comparing the stents gives PS to Bx 491 (d = 0.159), PS to GR-II (d = 0.837) and GR-II to Bx 492 (d = -0.764). This puts the stents in order from best to 493 494 worst as PS, Bx and GR-II. Comparing the stents using the threshold method of analysis, the PS stent 495 exposes 97.6% of the arterial tissue to WSSG > 496 200 N/m³ compared with 97.4% with the GR-II stent 497 and 98.9% with the Bx stent. These results are very 498 similar, and demonstrate that when analyzing the 499 WSSG, the threshold method is unable to distinguish 500 between the stents. 501

Wall Shear Stress Angle Gradient

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The distribution of the WSSAG is presented in 503 Fig. 8 using both semi-log and log-log plots to ensure 504 firstly, that the trend of the data is identifiable and 505 secondly, that all of the analyzed area is visible on the 506 plot. The mean value is highest for the Bx stent indi-507 cating that implantation of this stent leads to the 508 greatest alteration to the WSS direction. This is fol-509 lowed by the GR-II stent which produces the highest 510 511 standard deviation and lowest kurtosis. The PS has the best result with a mean WSSAG value of 2.405 rad/ 512 513 mm. The log-log histograms in Fig. 8 show that all stents have a small amount of area (approximately 514 0.03%) in the 100–200 rad/mm histogram range and 515 the GR-II and Bx have very small amounts of area 516 (approximately 0.001%) in the 200–300 rad/mm range. 517 Figure 4 shows the areas with the highest values of 518 WSSAG located around the S-connectors of the Bx 519 stent and also proximal and distal to the GR-II stent 520 struts which traverse the flow. Large areas of low 521



FIGURE 7. Distributions of the WSSG. The bars represent the amount of normalized area with WSSG values bounded by the tick marks on the abscissa. Bin widths are 100 N/m³.



FIGURE 8. Distributions of the WSSAG. The bars represent the amount of normalized area with WSSAG values bounded by the tick marks on the abscissa. Bin widths are distributed logarithmically. Additional log–log plots are provided to display all of the arterial area analyzed.

522 WSSAG are evident in between the struts of the PS 523 stent with values peaking near the small portions of the 524 struts that traverse the flow. Comparing the stents 525 gives PS to Bx (d = 0.338), PS to GR-II (d = 0.213) 526 and GR-II to Bx (d = 0.082). This puts the stents in 527 order from best to worst as PS, GR-II and Bx.

This variable provides a new perspective on the
alterations to the WSS induced by stent implantation
that is not commonly analyzed. Therefore, no threshold value exists in the literature to allow for comparison of techniques.

Oscillatory Shear Index

534 Implantation of the Bx stent creates the greatest 535 transient variation in the WSS direction as the mean of the OSI is 30 and 54% higher than for the GR-II and 536 PS stents, respectively. As shown in Fig. 9, the Bx stent 537 538 also has the highest standard deviation and lowest 539 kurtosis of the three stents indicating that this stent 540 performs the worst with regard to OSI. Comparatively 541 the PS stent has the lowest mean and standard 542 deviation with the highest kurtosis indicating that implantation of this stent creates the least alteration to 543 the transient WSS direction. Since the range of the OSI 544 is from 0 to 1, the mean values of OSI in the arteries 545 for the three stents are very low and as such, the dif-546 ferences in the distributions may be viewed as insig-547 nificant. However, the OSI quantifies transient 548 directional changes in flow direction which may only 549 be significant for IH in specific small areas of the artery 550 which could amplify the significance of these small 551 differences. The log-log plot shows small areas in the 552 0.4-0.5 range of OSI for the PS stent and small areas in 553 the 0.5-0.6 range for the GR-II and Bx stents. This 554 indicates regions where there are highly transient 555 directional changes in the WSS vector. Since the inlet 556 flow is unidirectional, Fig. 4 shows that most of the 557 stented artery has low values (<0.05) of OSI. The OSI 558 is slightly elevated in the proximal region for all stents 559 and has its peak values very close to the GR-II stent 560 wires and in select locations near the Bx struts and 561 S-connectors as shown in Fig. 4. Comparing the stents 562 gives PS to Bx (d = 0.620), PS to GR-II (d = 0.315) 563 and GR-II to Bx (d = 0.380). This puts the stents in 564 order from best to worst as PS, GR-II and Bx. 565

J. B. MURPHY AND F. J. BOYLE



FIGURE 9. Distributions of the OSI. The bars represent the amount of normalized area with OSI values bounded by the tick marks on the abscissa. Bin widths are distributed logarithmically. Additional log–log plots are provided to display all of the arterial area analyzed.

DISCUSSION

A new methodology is proposed to fully elucidate 567 568 the alterations in arterial WSS induced by stent 569 deployment. Four variables are employed in the methodology, each of which highlights a different type 570 571 of alteration of the arterial WSS which could lead to IH development. The proposed method of analyzing 572 573 the WSS-based variables provides a clear qualitative 574 and quantitative assessment of each variable distribu-575 tion making it possible to accurately assess the hemo-576 dynamic performance of a stent.

577 When the methodology is applied to the three stents, 578 the results have favored the PS as the implanted stent 579 which creates the least alteration to the WSS in the artery. The WSS, WSSG and WSSAG variables rank 580 581 the PS stent the highest. The OSI also favors the PS 582 stent; however the magnitudes of the mean OSI values 583 are quite small for the stents. Nevertheless, the histo-584 grams and contour plots do show that the GR-II and Bx stents create higher magnitudes of OSI around the 585 stent struts compared to the PS stent. The WSS, 586 587 WSSAG and OSI variables rank the GR-II ahead of 588 the Bx stent, with the only exception to the trend being 589 the WSSG where the GR-II ranks the lowest. Overall, the methodology indicates the stents hemodynamically 590 perform in the order of PS, GR-II and finally Bx. 591

Using the threshold method, the WSS variable 592 identifies the PS as the best stent, followed by the 593 GR-II and the Bx stents whereas the WSSG variable 594 yields inconclusive results. In this case, the threshold 595 method has managed to sufficiently distinguish 596 between the stents using one variable, and also rank 597 them in agreement with the proposed methodology. 598 However, the threshold method does not quantify the 599 complex hemodynamic disturbances that are identified 600 in this paper. Furthermore, the threshold method has 601 been proven unable to distinguish between stents in 602 previous studies,^{3,11,23} where the proposed method 603 may have proved more successful. An example of 604 complex stent induced hemodynamic disturbance is 605 shown in Fig. 5a where WSS vectors are shown to 606 quickly change magnitude and direction due to the 607 uneven prolapse shown in Fig. 5b. This leads to high 608 WSSG and WSSAG in this area which may well lead 609 to increased IH. The OSI in this area is also shown to 610 be high. These effects are not identified by the use of 611 the threshold method and such features could easily 612 have been overlooked in the previous studies. 613

TABLE 2. Angiographic restenosis rates for the PS, GR-II and Bx stents from five clinical trials.

Trial (year)	Trial design	No. of patients	Follow up (months)	Restenosis rate (%)
Lanskey <i>et al.</i> 27 (2000)	GR-II vs. PS	755	12	47.3 vs. 20.6
NIRVANA ² (2001)	NIR vs. PS	849	9	19.3 vs. 22.4
ASCENT ¹ (2001)	ML vs. PS	529	9	16.0 vs. 22.1
RAVEL DES ⁴⁰ (2002)	SES vs. Bx	283	6	0.0 vs. 23.4
ISAR-STERO II ³⁵ (2003)	ML vs. Bx	611	6	17.9 vs. 31.4

PS Palmaz Schatz (Cordis, Johnson and Johnson, NJ, USA), *NIR* NIR stent (Boston Scientific, MA, USA), *ML* Multilink (Guidant, CA, USA), *SES* Sirolimus-eluting stent.

614 The clinical performance of these stents is available from the results of several clinical trials shown in 615 616 Table 2. The most commonly used method of com-617 parison of BMSs is angiographic restenosis rates, defined as percentage of patients with >50% renar-618 619 rowing of the target vessel at follow up. The PS and GR-II stents were directly compared in a trial con-620 sisting of 755 patients with de novo lesions.²⁷ Reste-621 622 nosis rates were found to be statistically significant 623 (p < 0.001) between the two stents with values of 47.3 624 and 20.6% for the GR-II and PS, respectively. A 625 possible factor in the poor GR-II result is the "clam-626 shell" deployment which is likely to cause more arterial 627 damage than for the slotted-tube type stents such as 628 the PS. "Infrequent optimal GR-II size selection" was 629 also noted in the study which would likely contribute 630 to poor stent performance. The PS stent has also been involved in the stent equivalency trials ASCENT⁷ and 631 NIRVANA² and had restenosis rates of 22.1 and 632 633 22.4%, respectively. There were similar criteria for 634 inclusion in these three trials such as native vessel diameter of greater than 3 mm, de novo lesions, and 635 636 similar study end points. The Bx stent had a restenosis rate of 31.4% in the ISAR-STEREO-II³⁵ which had 637 638 patients with de novo and restenotic lesions, but similar vessel diameter and trial end points. The Bx stent 639 640 also had a restenosis rate of 23.4% in the control arm of the RAVAL DES trial⁴⁰ where inclusion criteria 641 642 were a de novo lesion with native vessel diameter 643 between 2.5 and 3.5 mm. While one must be cautious 644 when comparing the results of different stent trials, it 645 would appear that the PS stent has the best in vivo 646 results, followed in turn by the Bx and GR-II stents. 647 From the results of the current study it would appear that hemodynamics are influential in the restenosis 648 rates associated with the PS and Bx stents. From the 649 650 CFD results, the GR-II stent performed worse than the 651 PS stent hemodynamically. However, it would have to 652 be concluded that other influential factors were also to 653 blame for the stents poor clinical performance as it had 654 such a severe restenosis rate.

Limitations to the methodology employed in this paper include the assumptions of fully-developed laminar flow, a rigid stent and arterial wall, and the 657 omission of a stenotic plaque. Whilst the depth of 658 tissue prolapse is based on FEA data,³⁶ the shape of 659 the protruding tissue is a further limitation as it is 660 idealized and based entirely on the geometry of the 661 stent. Curvature and taper of the artery have also been 662 omitted in the analysis for simplicity. The outlet 663 boundary condition of a fixed pressure is a limitation 664 creating a non-physiological transient pressure in the 665 CFD model. However, this outlet boundary condition 666 is the standard practice for modeling of pulsatile flow 667 in arteries.^{3-5,13,21,23,25,37} With this boundary condi-668 tion, the CFD software calculates the necessary inlet 669 pressure to drive the flow. The velocity which is spec-670 ified at the inlet should therefore maintain reasonable 671 672 physiological accuracy in the computational domain.

The objective of this work is to introduce a more complete method of analyzing the alterations to WSS acting on the living tissue in the stented artery. As such, this method of stent assessment should assist in stent design in the future and is applicable to bare metal, drug-eluting and any future stents that alter the WSS in the artery after implantation. 673 674 675 676 677 678 678 678 678 679

ACKNOWLEDGMENTS 682

This paper is the result of 4 years of effort and was683supported by the Department of Mechanical Engi-
neering in the Dublin Institute of Technology (DIT)685and also the Irish Research Council for Science Engi-
neering and Technology (IRCSET).686

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